



Robot Mechanisms: 60 (Intelligent Systems, Control and Automation: Science and Engineering)

Jadran Lenarcic, Tadej Bajd, Michael M. Staniši?

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This book provides a comprehensive introduction to the area of robot mechanisms, primarily considering industrial manipulators and humanoid arms. The book is intended for both teaching and self-study. Emphasis is given to the fundamentals of kinematic analysis and the design of robot mechanisms. The coverage of topics is untypical. The focus is on robot kinematics. The book creates a balance between theoretical and practical aspects in the development and application of robot mechanisms, and includes the latest achievements and trends in robot science and technology.



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