



Newton-Euler Dynamics

Mark D. Ardema

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Most books on this subject are designed for elective courses in 'intermediate dynamics' covering advanced Newtonian and introductory Lagrangian methods. Such books do not give adequate emphasis to advanced topics in Newton-Euler dynamics. Because the first required course in dynamics usually concentrates on 2-D dynamics, important 3-D problems are left to a further course. Examples are robots, automated manufacturing devices, aerospace vehicles, and biomechanical components. This material cannot be covered adequately in one course if it is to be shared with an introduction to Lagrangian methods. This text is devoted to application of Newton-Euler methods to complex, real-life 3-D dynamics problems; it essentially completes this topic.

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